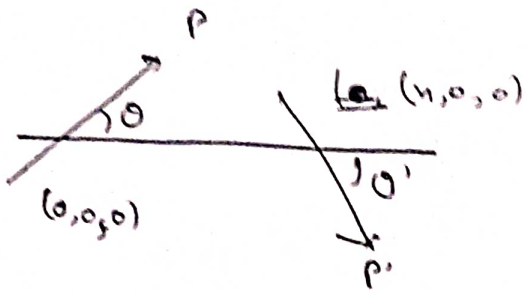


Q ①



$$\vec{E}(a,0,0) = \frac{2P \cos \theta}{k^3} k \hat{i} - \frac{P \sin \theta}{k^2} \hat{j}$$

Potential Energy of P'

$$= -\vec{P}' \cdot \vec{E}$$

$$= - \left[ \frac{2kPP' \cos \theta \cos \theta'}{k^3} + \frac{kPP' \sin \theta \sin \theta'}{k^2} \right]$$

P' would be in a configuration where its PE is minimised.  $\Rightarrow$   ~~$\vec{P} \parallel \vec{E}$~~  is maximum  $\vec{P}' \cdot \vec{E}$  is maximum

$$f(\theta') = 2c \cos \theta \cos \theta' + c \sin \theta \sin \theta'$$

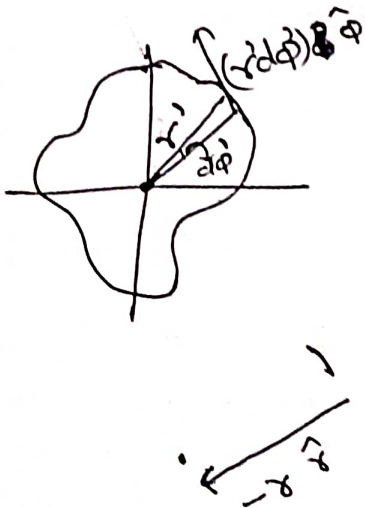
$$(c = \frac{kPP'}{k^2})$$

$$f'(\theta') = -2c \cos \theta \sin \theta' + c \sin \theta \cos \theta' = 0$$

$$\tan \theta = \tan \theta'$$

$$\theta' = \tan^{-1} \left( \frac{\tan \theta}{2} \right)$$

Q ② (a)



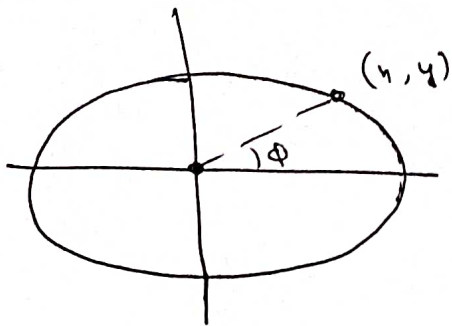
From Biot Savart's Law

$$B = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times (\vec{r}'' - \vec{r}')}{|\vec{r}'' - \vec{r}'|^3}$$

$$= \frac{\mu_0 I}{4\pi} \int_{\text{wire}} \frac{(r' d\phi \hat{\phi}) \times (-r' \hat{z})}{r''^3}$$

$$= \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{d\phi'}{r'(\phi')} \hat{z} = \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{d\phi}{r(\phi)} \hat{z}$$

(b)



$$\tan \phi = \frac{y}{x}$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\frac{x^2}{a^2} + \frac{x^2 \tan^2 \phi}{b^2} = 1$$

$$x^2 = \frac{a^2 b^2}{b^2 + a^2 \tan^2 \phi}$$

$$r^2 = x^2 + y^2 = x^2 \sec^2 \phi = \frac{a^2 b^2 \sec^2 \phi}{b^2 + a^2 \tan^2 \phi} = \frac{a^2 b^2}{b^2 + (a^2 - b^2) \sin^2 \phi}$$

$$= \frac{a^2}{1 - \left(1 - \frac{a^2}{b^2}\right) \sin^2 \phi}$$

$$= \frac{a^2}{1 - \left(1 - \frac{a^2}{b^2}\right) \sin^2 \phi}$$

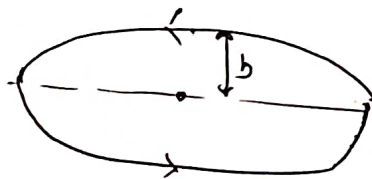
$$\vec{B} = \frac{\mu_0 I}{4\pi} 4 \int_0^{\pi/2} \frac{d\phi}{a} \sqrt{1 - \left(1 - \frac{a^2}{b^2}\right) \sin^2 \phi}$$

$$\vec{B} = \frac{\mu_0 I}{\pi a} \int_0^{\pi/2} d\phi \sqrt{1 - \left(1 - \frac{a^2}{b^2}\right) \sin^2 \phi}$$

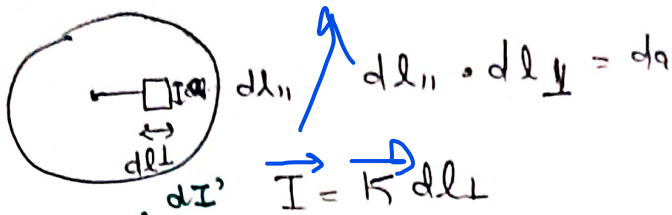
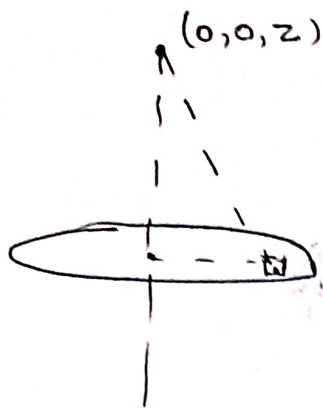
(i)  $a = b \Rightarrow \vec{B} = \frac{\mu_0 I}{2a}$

(ii)  $a \rightarrow \infty$

$\frac{\mu_0 I}{\pi b}$  (double wire)



(c)



$$\hat{r} = z \hat{z}$$

$$\hat{r}' = r' \hat{r} + \phi' \hat{\phi}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{(\vec{K} d\vec{l}_\perp) \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d\vec{l}'$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{(K \hat{\phi}) \times (z \hat{z} - r' \hat{r} - \phi' \hat{\phi})}{(r'^2 + z^2)^{3/2}} r' dr' d\phi'$$

$$= \frac{\mu_0}{4\pi} \int_0^R \int_0^{2\pi} \frac{(Kz \hat{r} + r'K \hat{z})}{(r'^2 + z^2)^{3/2}} r' dr' d\phi'$$

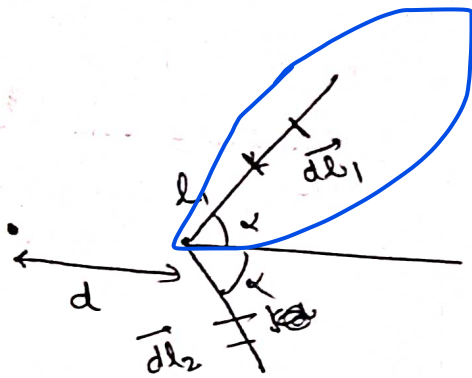
$$= \frac{\mu_0}{4\pi} \int_0^R \int_0^{2\pi} \frac{Kz r' (-\sin\phi' \hat{n} + \cos\phi' \hat{y})}{(r'^2 + z^2)^{3/2}} + \frac{K(r')^2 dr' d\phi' \hat{z}}{(r'^2 + z^2)^{3/2}}$$

$$= \frac{\mu_0}{4\pi} \int_0^R \int_0^{2\pi} \frac{K(r')^2}{(r'^2 + z^2)^{3/2}} dr' d\phi' \hat{z}$$

Substitute  $r' = z \tan \theta$   $\left\{ R = z \tan \alpha \right\}$

Final Ans  $\rightarrow \frac{\mu_0 K}{2} \left[ \ln(\sec \alpha + \tan \alpha) - \sin \alpha \right]$

6



$$\vec{B} = \int d\vec{B}_1 + \int d\vec{B}_2$$

$$= \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}_1 \times (\vec{r} - \vec{r}_1')}{|\vec{r} - \vec{r}_1'|^3} + \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}_2 \times (\vec{r} - \vec{r}_2')}{|\vec{r} - \vec{r}_2'|^3}$$

$$d\vec{l}_2 = dl_2' \cos \alpha \hat{n} - dl_2' \sin \alpha \hat{y} \quad d\vec{l}_1 = -dl_1' \cos \alpha \hat{n} - dl_1' \sin \alpha \hat{y}$$

$$\vec{r} = -d \hat{n}$$

$$\vec{r} = -d \hat{n}$$

$$\vec{r}_2' = l_2' \cos \alpha \hat{n} - l_2' \sin \alpha \hat{y} \quad \vec{r}_1' = l_1' \cos \alpha \hat{n} + l_1' \sin \alpha \hat{y}$$

$$\vec{B}_1 = \frac{\mu_0 I}{4\pi} \int_0^\infty \frac{(-dl_1' \cos \alpha \hat{n} - dl_1' \sin \alpha \hat{y}) \times ((-d - l_1' \cos \alpha) \hat{n} - l_1' \sin \alpha \hat{y})}{d^2 + (l_1')^2 + 2dl_1' \cos \alpha}$$

$$= \frac{\mu_0 I}{4\pi} \int_0^\infty \frac{(l_1' \sin \alpha \cos \alpha - l_1' \sin \alpha \cos \alpha - d \sin \alpha) \hat{z} \cdot dl_1'}{(d^2 + (l_1')^2 + 2dl_1' \cos \alpha)^{3/2}}$$

$$= -\frac{\mu_0 I d \sin \alpha \hat{z}}{4\pi} \int_0^\infty \frac{1}{[(l_1' + d \cos \alpha)^2 + (d \sin \alpha)^2]^{3/2}} dl_1'$$

$$l_1' + d \cos \alpha = \frac{d \sin \alpha}{\tan \theta}$$

$$d \sin \alpha = \frac{d \sin \alpha}{\tan \theta} \tan \theta$$

$$\frac{l_1' + d \cos \alpha}{d \sin \alpha} = \tan \theta$$

$$dl_1' = \sec^2 \theta d\theta (d \sin \alpha)$$

$$= -\frac{\mu_0 I \hat{z}}{4\pi (d \sin \alpha)^2}$$

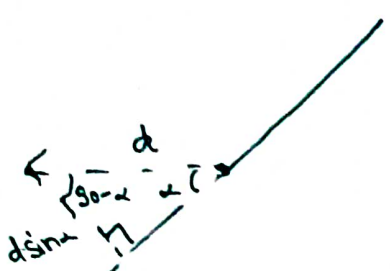
$$= \frac{-\mu_0 I \hat{z}}{4\pi (d \sin \alpha)^2} \int_{\frac{\pi - \alpha}{2}}^{\frac{\pi + \alpha}{2}} \frac{\sec^2 \theta \cdot d\theta}{\sec^3 \theta} = \frac{-\mu_0 I (1 - \cos \alpha) \hat{z}}{4\pi (d \sin \alpha)}$$

$$\vec{B}_2 = \vec{B}_1 = \frac{-\mu_0 I (1 - \cos \alpha) \hat{z}}{4\pi d \sin \alpha}$$

$$\vec{B} = \frac{-\mu_0 I \tan \frac{\alpha}{2} \hat{z}}{2\pi d}$$

## Additional remarks about Q6

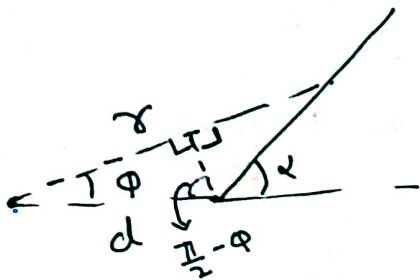
(1) JEE DAYS !!



$$B = \frac{\mu_0}{4\pi} \frac{(\sin\theta_1 + \sin\theta_2)}{d \sin\alpha} = \frac{\mu_0}{4\pi} \frac{(\sin(-(90-\alpha)) + \sin 90)}{d \sin\alpha}$$

$$= \frac{\mu_0}{4\pi} \frac{(1 - \cos\alpha)}{d \sin\alpha}$$

(ii) could also be solved using result of Q(a)



$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{d\phi}{r(\phi)} = \frac{\mu_0 I}{4\pi} \int_0^{\alpha} \frac{d\phi}{r(\phi)}$$

$$r = \frac{d \cos\phi + d \sin\alpha}{\cos(\frac{\pi}{2} - \phi)}$$

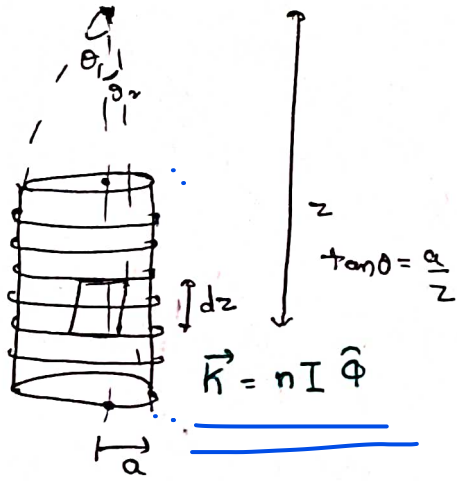
$$= \frac{d \cos\phi + d \sin\alpha}{\sin(\alpha - \phi)}$$

$$= \frac{d \sin\alpha}{\sin(\alpha - \phi)}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_0^{\alpha} \frac{d\phi \sin(\alpha - \phi)}{d \sin\alpha} = \frac{\mu_0 I}{4\pi} \frac{(1 - \cos\alpha)}{d \sin\alpha}$$



9



$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{K} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \cdot d\vec{a}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{(nI \hat{\phi}) \times (z \hat{z} - a \hat{r} - \phi \hat{\phi})}{(a^2 + z^2)^{3/2}} a d\phi dz$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{(nI z \hat{r} - nI a \hat{z})}{(a^2 + z^2)^{3/2}} a d\phi dz$$

$$\tan \theta = a/z$$

$$\sec^2 \theta \cdot d\theta = -\frac{a}{z^2} dz = -\tan^2 \theta \frac{dz}{a}$$

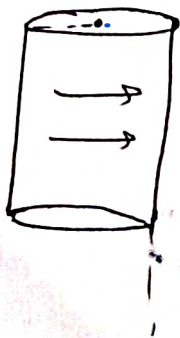
$$dz = -\frac{a}{\sin^2 \theta}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int_0^{2\pi} \int_{\theta_1}^{\theta_2} \frac{nI a}{\tan \theta} \frac{(-\sin \phi \hat{n} + \cos \phi \hat{y})}{a^2 \cos \theta \sin^3 \theta} d\phi \left( \frac{-a^2}{\sin^2 \theta} \right) d\theta$$

$$+ \int_0^{2\pi} \int_{\theta_1}^{\theta_2} \frac{nI a \hat{z}}{a^2 \cos \theta \sin^3 \theta} \left( \frac{a^2}{\sin^2 \theta} \right) \cdot d\phi d\theta$$

$$\vec{B} = \frac{\mu_0 n I}{4\pi} \int_0^{2\pi} d\phi \int_{\theta_1}^{\theta_2} \sin \theta d\theta \hat{z} = \frac{\mu_0 n I}{2} (\cos \theta_1 - \cos \theta_2) \hat{z}$$

(i) Half solenoid  
 $\theta_1 = \pi/2, \theta_2 = 0$



$$\vec{B} = \frac{\mu_0 n I}{2} \hat{z}$$

(ii) Infinite solenoid



$\theta_1 \rightarrow \pi$   
 $\theta_2 \rightarrow 0$

$$\vec{B} = \mu_0 n I \hat{z}$$